



**SOLIDWORKS MOTION**

PREREQUISITES	LENGTH	DESCRIPTION
<ul style="list-style-type: none"> <li>■ Knowledge of SOLIDWORKS required. Basics of Motion Manager and basic mechanical engineering concepts is recommended.</li> </ul>	<p>2 Days</p>	<ul style="list-style-type: none"> <li>■ This course has been designed for new SOLIDWORKS Motion users who would like to learn to perform motion analysis on their designs. The course provides an in-depth session on the basics of building, simulating and refining a mechanical design system.</li> </ul>
<p>► <b>INTRO TO MOTION SIMULATION &amp; FORCES</b></p>		<p>► <b>ADVANCED CONTACT</b></p>
<ul style="list-style-type: none"> <li>■ Objectives</li> <li>■ Basic Motion Analysis</li> <li>■ Case Study: Car Jack Analysis</li> <li>■ Driving Motion</li> <li>■ Forces</li> <li>■ Understanding Forces</li> <li>■ Results</li> <li>■ Exercise 1: 3D Fourbar Linkage</li> </ul>		<ul style="list-style-type: none"> <li>■ Contact Forces</li> <li>■ Case Study: Latching Assembly</li> <li>■ Motor Input and Force Input Types</li> <li>■ Force Functions</li> <li>■ STEP Function</li> <li>■ Contact: Solid Bodies</li> <li>■ Geometrical Description of Contacts</li> <li>■ Integrators</li> <li>■ Instability Points</li> <li>■ Modifying Result Plots</li> <li>■ Exercise 6: Hatchback</li> <li>■ Exercise 7: Conveyor Belt (No Friction)</li> <li>■ Exercise 8: Conveyor Belt (With Friction)</li> </ul>
<p>► <b>BUILD MOTION MODEL &amp; POST-PROCESSING</b></p>		<p>► <b>CURVE TO CURVE CONTACT</b></p>
<ul style="list-style-type: none"> <li>■ Creating Local Mates</li> <li>■ Case Study: Crank Slider Analysis</li> <li>■ Mates</li> <li>■ Local Mates</li> <li>■ Function Builder</li> <li>■ Importing Data Points</li> <li>■ Power</li> <li>■ Plotting Kinematic Results</li> <li>■ Exercise 2: Piston</li> <li>■ Exercise 3: Trace Path</li> </ul>		<ul style="list-style-type: none"> <li>■ Case Study: Geneva Mechanism</li> <li>■ Curve to Curve Contact</li> <li>■ Solid Bodies vs. Curve to Curve Contact</li> <li>■ Solid Bodies Contact Solution</li> <li>■ Exercise 9: Conveyor Belt (Curve to curve contact with friction)</li> </ul>
<p>► <b>INTRO TO CONTACTS, SPRINGS &amp; DAMPERS</b></p>		<p>► <b>CAM SYNTHESIS</b></p>
<ul style="list-style-type: none"> <li>■ Contact and Friction</li> <li>■ Case Study: Catapult</li> <li>■ Translational Spring</li> <li>■ Exercise 4: The Bug</li> <li>■ Exercise 5: Door Closer</li> </ul>		<ul style="list-style-type: none"> <li>■ Case Study: Cam Synthesis</li> <li>■ Trace Path</li> <li>■ Exporting Trace Path Curves</li> <li>■ Exercise 10: Desmodromic Cam</li> <li>■ Exercise 11: Rocker Cam Profile</li> </ul>



### SOLIDWORKS MOTION

#### ► MOTION OPTIMIZATION

- Motion Optimization
- Case Study: Medical Examination Chair
- Sensors
- Optimization Analysis

#### ► FLEXIBLE JOINTS

- Flexible Joints
- Case Study: System with Rigid Joints
- Calculation of Wheel Input Motion
- Understanding Toe Angles
- System with Flexible Joints

#### ► REDUNDANCIES

- Redundancies
- Case Study: Door Hinges
- Using Flexible Joints Option to Remove Redundancies
- How to Check For Redundancies
- Typical Redundant Mechanisms
- Exercise 12: Dynamic Systems
- Exercise 13: Dynamic Systems 2
- Exercise 14: Kinematic Mechanism
- Exercise 15: Zero Redundancy Model-Part I
- Exercise 16: Zero Redundancy Model-Part 2 (Optional)
- Exercise 17: Removing Redundancies with Bushings
- Exercise 18: Catapult

#### ► EXPORT TO FEA

- Exporting Results
- Case Study: Drive Shaft
- Load Bearing Faces
- Export of Loads
- Direct Solution in SOLIDWORKS Motion
- Exercise 19: Export to FEA

#### ► EVENT BASED SIMULATION

- Event Based Simulation
- Case Study: Sorting Device
- Servo Motors
- Sensors
- Task

#### ► DESIGN PROJECT (OPTIONAL)

- Design Project
- Case Study: Surgical Shear - Part I
- Self Guided Problem - Part I
- Self Guided Problem - Part 2
- Problem Solution - Part I
- Creating the Force Function
- Force Expression
- Case Study: Surgical Shear - Part 2